

# Symmetry and cosmology in Cartan language for geometric theories of gravity

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  - Planar symmetry for gravitational waves.
  - Spherical symmetry for stellar objects.
  - Axial symmetry for rotating systems.
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  - Affine geometry
  - Riemann-Cartan geometry
  - Riemannian geometry
  - Weizenböck geometry
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# Motivation

- Spacetime symmetries important in physics / gravity:
  - Planar symmetry for gravitational waves.
  - Spherical symmetry for stellar objects.
  - Axial symmetry for rotating systems.
  - Homogeneous and isotropic cosmological symmetry.
- Cartan geometry provides unified description of. . .
  - Affine geometry
  - Riemann-Cartan geometry
  - Riemannian geometry
  - Weizenböck geometry
  - . . .
- **Framework can be generalized to observer space:**
  - All measurements are performed by observers.
  - Measurements depend on observer's frame (velocity).
  - Quantum gravity: possible non-tensorial velocity dependence.
  - Observer space: space of all physical velocities.
  - Geometry of observer space naturally given by Cartan geometry.

# Complete lifts of vector fields

- **Tangent bundle lift:**

- Diffeomorphism group  $\varphi : \mathbb{R} \times M \rightarrow M$  induces  $\hat{\varphi} : \mathbb{R} \times TM \rightarrow TM$ :

$$\hat{\varphi}_t = \varphi_{t*}.$$

- $\hat{\varphi}$  generated by vector field  $\hat{\xi} \in \text{Vect}(TM)$ .
- In coordinates  $(x^a, y^a)$  on  $TM$ :

$$\hat{\xi} = \xi^a \partial_a + y^b \partial_b \xi^a \bar{\partial}_a.$$

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- Frame bundle lift:

- Frame bundle  $FM = \text{GL}(M)$ : linear maps  $f \rightarrow T_x M, x \in M$ .
- Diffeomorphism group  $\varphi : \mathbb{R} \times M \rightarrow M$  induces  $\bar{\varphi} : \mathbb{R} \times FM \rightarrow FM$ :

$$\bar{\varphi}_t(f) = \varphi_{t*} \circ f.$$

- $\bar{\varphi}$  generated by vector field  $\bar{\xi} \in \text{Vect}(FM)$ .
- In coordinates  $(x^a, f_i^a)$  on  $FM$ :

$$\bar{\xi} = \xi^a \partial_a + f_i^b \partial_b \xi^a \bar{\partial}_a^i.$$

- Klein geometry: Lie group  $G$  with closed subgroup  $H \subset G$ .
- Cartan geometry  $(\pi : \mathcal{P} \rightarrow M, A)$  modeled on  $G/H$ :
  - Principal  $H$ -bundle  $\pi : \mathcal{P} \rightarrow M$
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- Conditions on Cartan connection  $A \in \Omega^1(\mathcal{P}, \mathfrak{g})$ :
  - For each  $p \in \mathcal{P}$ ,  $A_p : T_p\mathcal{P} \rightarrow \mathfrak{g}$  is linear isomorphism.
  - Equivariance:  $(R_h)^*A = \text{Ad}(h^{-1}) \circ A \quad \forall h \in H$ .
  - $A$  restricts to Maurer-Cartan form of  $H$  on  $\ker \pi_*$ .



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- Equivalent: **fundamental vector fields**  $\underline{A} : \mathfrak{g} \rightarrow \text{Vect}(\mathcal{P})$ :
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  - $\underline{A}$  restricts to canonical vector fields on  $\mathfrak{h}$ .

# First order reductive models

- **First order Cartan geometry:**

- Adjoint representations of  $H \subset G$  on  $\mathfrak{g}$  and  $\mathfrak{h}$ .
- Quotient representation of  $H$  on  $\mathfrak{g}/\mathfrak{h}$  is faithful.

⇒ “Fake tangent bundle”  $\mathcal{T} = \mathcal{P} \times_H \mathfrak{g}/\mathfrak{h}$ .

⇒  $\mathcal{P}$  is “fake frame bundle”: “admissible” frames  $\mathfrak{g}/\mathfrak{h} \rightarrow \mathcal{T}_x$  for  $x \in M$ .

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- **Reductive Cartan geometry:**

- Direct sum  $\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{z}$  of vector spaces.
- $\mathfrak{h}$  and  $\mathfrak{z}$  are subrepresentations of  $\text{Ad } H$  on  $\mathfrak{g}$ .

⇒ Cartan connection  $A = \omega + e$  splits:  $\omega \in \Omega^1(\mathcal{P}, \mathfrak{h})$  and  $e \in \Omega^1(\mathcal{P}, \mathfrak{z})$ .

⇒  $e$  induces isomorphism  $\mathcal{T} \cong TM$ .

⇒  $e$  induces isomorphism  $\mathcal{P} \cong P \subset FM$ .

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⇒ Cartan geometry  $(\tilde{\pi} : P \rightarrow M, \tilde{A})$  with  $\tilde{A} = \tilde{\omega} + \tilde{e}$ .

- $\tilde{e}$ : solder form on  $P \subset FM$ .

- Drop tilde and consider Cartan geometries on  $\mathcal{P} \equiv P \subset FM$ .

# Symmetries in Cartan language

- Symmetry generated by **vector field**  $\xi \in \text{Vect}(M)$ .
- $\Rightarrow$  Frame bundle lift  $\bar{\xi} \in \text{Vect}(FM)$  of  $\xi$ .

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- **Solder form  $e \in \Omega^1(P, \mathfrak{g})$ :**
  - For  $v \in T_pP$  defined by  $e(v) = p^{-1}(\pi_*(v))$ .
  - Satisfies  $\bar{\varphi}^*e = e$  for any diffeomorphism  $\varphi : M \rightarrow M$ .
- ⇒  $\mathcal{L}_{\bar{\xi}}e = 0$  for any  $\xi \in \text{Vect}(M)$ .
- ⇒ Only need to check  $\mathcal{L}_{\bar{\xi}}\omega = 0$ .

# The orthogonal model geometry

- Model geometry for 3 + 1-dimensional spacetime:

$$G = \begin{cases} \text{SO}_0(4, 1) & \Lambda > 0 \\ \text{ISO}_0(3, 1) & \Lambda = 0 \\ \text{SO}_0(3, 2) & \Lambda < 0 \end{cases}, \quad H = \text{SO}_0(3, 1).$$

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⇒ **Cartan geometry**  $(\pi : P \rightarrow M, A) \iff$  **metric spacetime**:

- Metric  $g$  derived from solder form  $e$ .
- Metric-compatible connection  $\Gamma$  derived from  $\omega$ .
- $P \subset FM$  is orthonormal frame bundle of  $(M, g)$ .

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- **Symmetry of Cartan connection under vector field  $\xi \in \text{Vect}(M)$ :**
  - $\bar{\xi}$  is tangent to  $P \Leftrightarrow \mathcal{L}_{\bar{\xi}}g = 0$ .
  - $\mathcal{L}_{\bar{\xi}}\omega = 0 \Leftrightarrow \mathcal{L}_{\xi}\Gamma = 0$ .

- **Riemann-Cartan spacetime:**

- Metric  $g$  and torsion  $T$  determine connection

$$\Gamma^a_{bc} = \frac{1}{2}g^{ad}(\partial_b g_{dc} + \partial_c g_{bd} - \partial_d g_{bc} - g_{be}T^e_{cd} - g_{ce}T^e_{bd}) + \frac{1}{2}T^a_{cb}.$$

⇒ Cartan geometry with Cartan curvature  $F = dA + A \wedge A \in \Omega^2(P, \mathfrak{g})$ .

⇒ Symmetry of Cartan geometry  $\Leftrightarrow \mathcal{L}_\xi g = 0, \mathcal{L}_\xi T = 0$ .

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- **Riemannian spacetime:**

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- Weizenböck spacetime:

- Vielbein  $h$  determines Weizenböck connection

$$\Gamma^a_{bc} = h_i^a \partial_c h_b^i.$$

⇒ Cartan geometry with Cartan curvature  $F = dA + A \wedge A \in \Omega^2(P, \mathfrak{g})$ .

⇒ Symmetry of Cartan geometry  $\Leftrightarrow \mathcal{L}_\xi h = \lambda h, \lambda \in \mathfrak{h}$ .

# The observer space model

- **Model geometry for 3 + 3 + 1-dimensional observer space:**

$$G = \begin{cases} \text{SO}_0(4, 1) & \Lambda > 0 \\ \text{ISO}_0(3, 1) & \Lambda = 0 \\ \text{SO}_0(3, 2) & \Lambda < 0 \end{cases}, \quad H = \text{SO}_0(3, 1), \quad K = \text{SO}(3).$$

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⇒ Split  $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{h} \oplus \vec{\mathfrak{z}} \oplus \mathfrak{z}^0$  of the Poincaré algebra:

- $\mathfrak{k}$ : spatial rotations.
- $\mathfrak{h}$ : Lorentz boosts.
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- **Cartan geometry** ( $\pi : P \rightarrow O, A$ ) modeled on  $G/K$  with  $P \subset FO$ :
  - ⇒ Split  $A = \Omega + b + \vec{e} + e^0$  of the Cartan connection.
  - ⇒ Induces split  $TP = RP \oplus BP \oplus \vec{H}P \oplus H^0P$ .



# Symmetries of observer space

- Structures induced by Cartan geometry ( $\pi : P \rightarrow O, A$ ):
  - Tangent bundle split  $TO = VO \oplus \vec{HO} \oplus H^0O$ .
  - Projectors  $P_V, P_{\vec{H}}, P_{H^0}, P_H = P_{\vec{H}} + P_{H^0}$  onto subbundles.
  - Vector bundle isomorphism  $\Theta : VO \rightarrow \vec{HO}$ .
  - “Time translation” vector field  $\mathbf{r} \in \Gamma(H^0O)$ .

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- $\Xi \in \text{Vect}(O)$  generates “spacetime” diffeomorphism if:
  - Boost component of  $\Xi$  is time derivative of spatial translation:

$$P_H \circ \mathcal{L}_{\mathbf{r}}(P_H \circ \Xi) = \Theta \circ P_V \circ \Xi.$$

- $\Xi$  does not depend on vertical directions:

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  - Induces lifted vector fields  $\hat{\xi} \in \text{Vect}(TM)$  and  $\bar{\xi} \in \text{Vect}(FM)$ .

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- Further research topics:
  - Construct observer spaces with particular symmetries.
  - Local Lorentz invariance of teleparallel theories?